



**AGH UNIVERSITY OF SCIENCE
AND TECHNOLOGY**

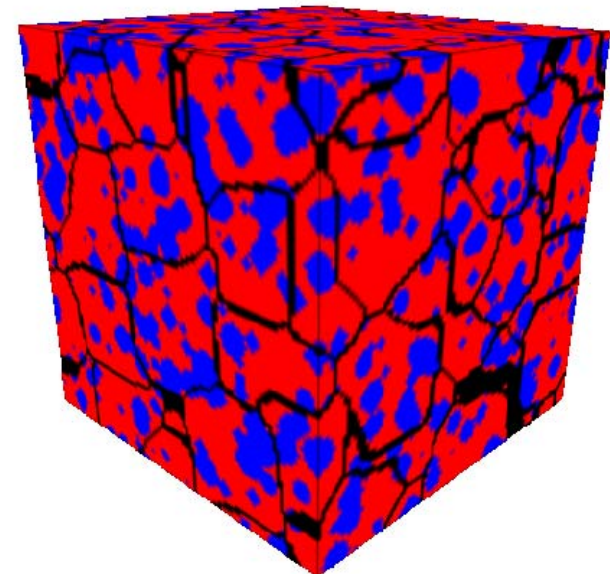


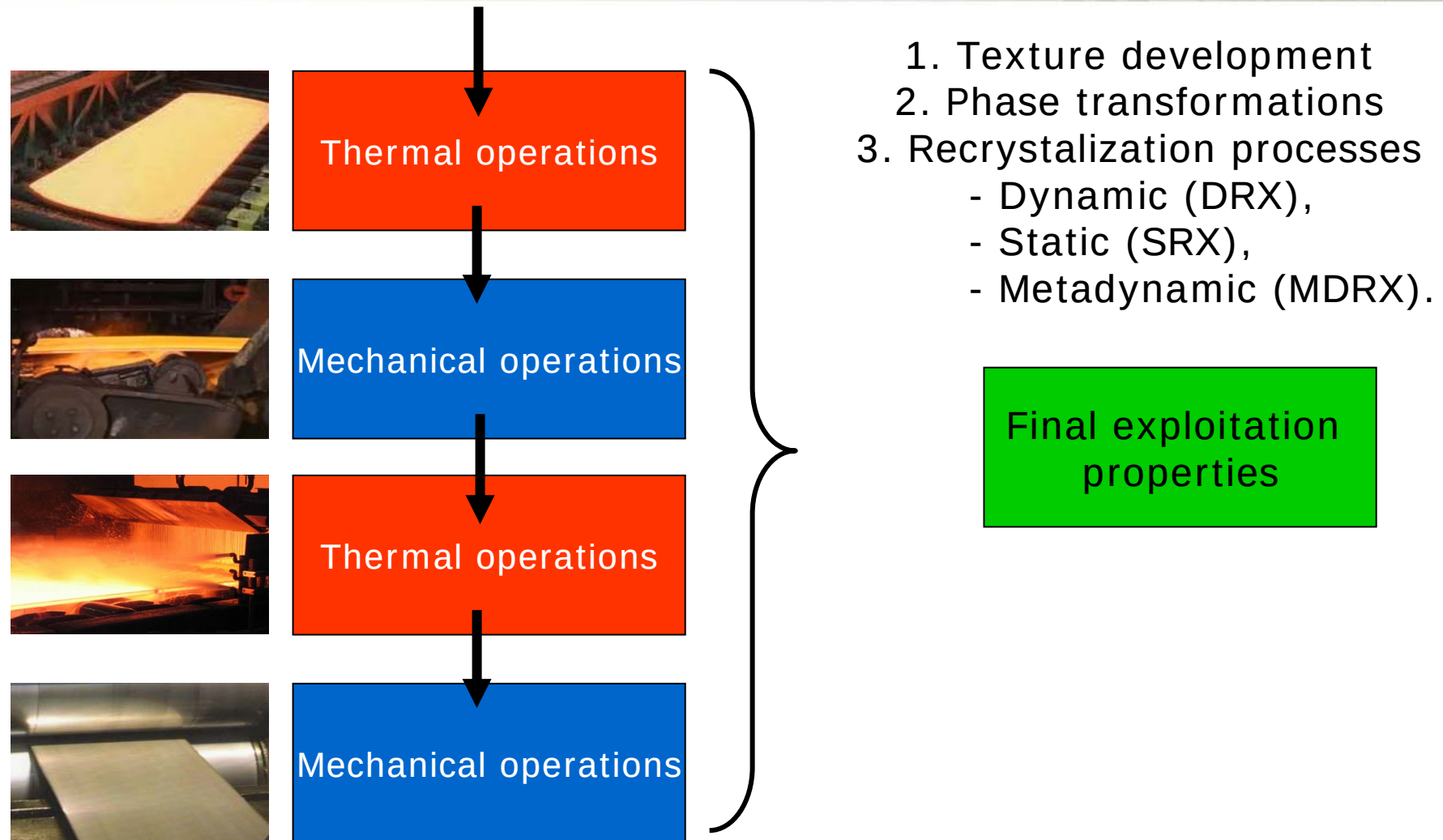
Study of the parallelization possibility of a Monte Carlo grain growth algorithm.

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Zakopane 01.03.13

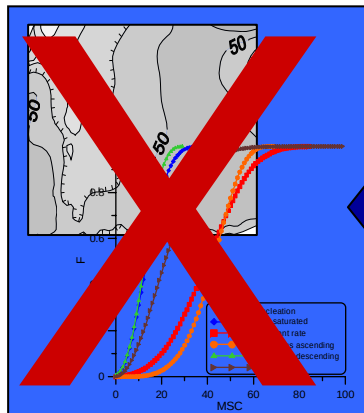
1. Motivation
2. Monte Carlo model for grain growth simulation
3. Parallelization idea
4. Results
5. Conclusions and plans for future work



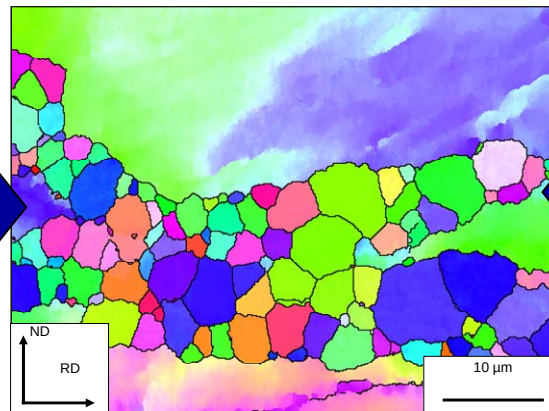


Numerical modelling of static recrystalization (SRX)

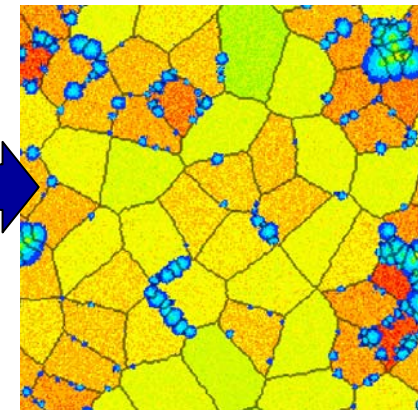
Conventional approaches



Real material



Discrete Models e.g. CA, MC

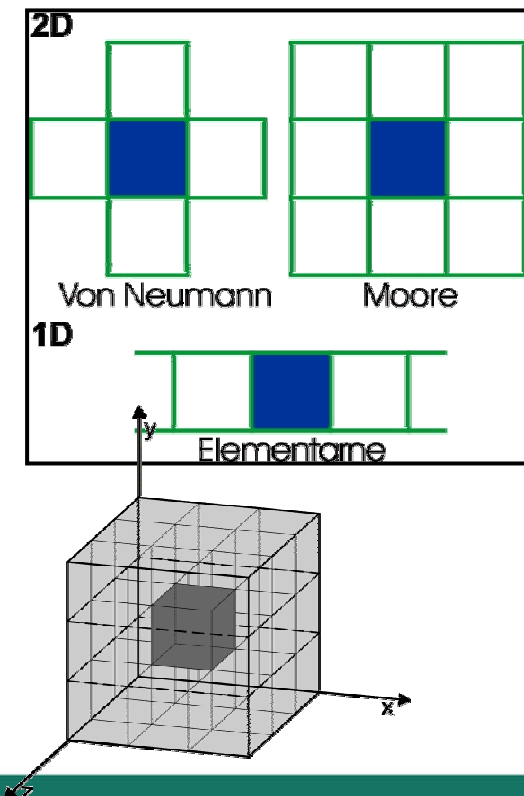


The main aim of this work is development of MC grain growth algorithm for farther SRX simulation.

MC method

The main idea of the Monte Carlo technique is to divide a specific part of the material into one-, two-, or three-dimensional lattices of cells, where cells have clearly defined interaction rules between each other. MC simulations have probabilistic character and it is based on minimization of system energy.

- **MC space** - finite set of cells, where each cell is described by a set of internal variables describing the state of a cell.
- **Neighborhood** — describes the closest neighbors of a particular cell. It can be in 1D, 2D and 3D space.
- **Energy minimization** - E, the energy value of each cell in the lattice is determined by the states of its neighbors and the cell itself.

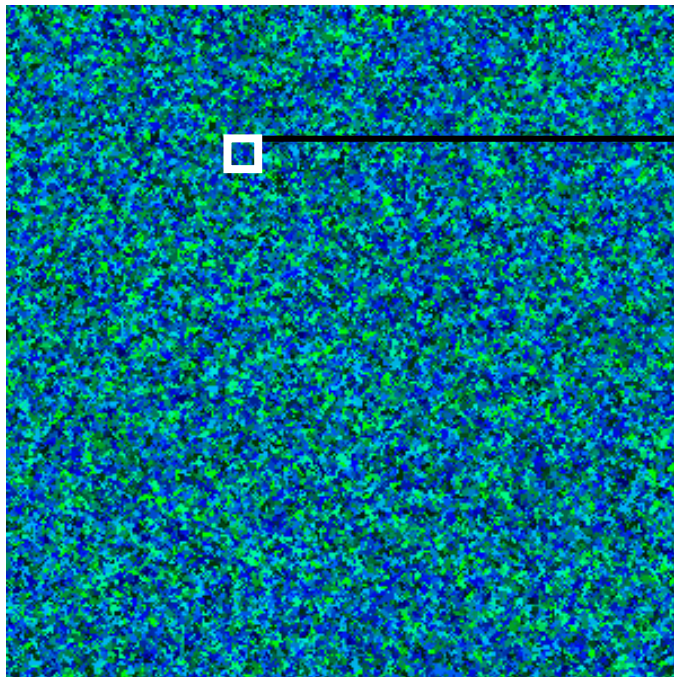




AGH MC method assumptions



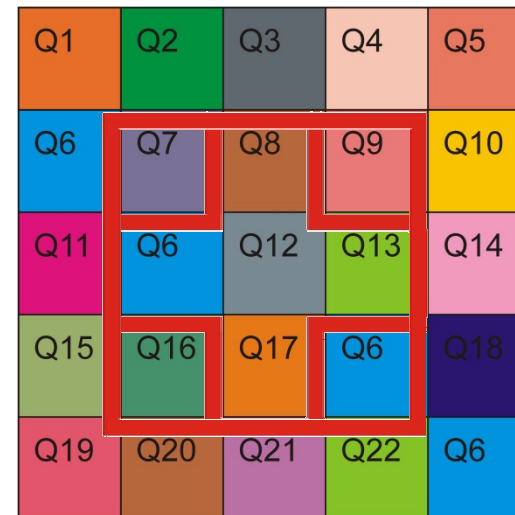
n = 50
↓
State
number



1 MCS

Cells in the same state represent particular grain

$$\Omega = \{Q_0, \dots, Q_{n-1}\}$$



Algorithm steps:

Step 1: Random selection of element with specific orientation.

Q1	Q1	Q2
Q3	Q3	Q2
Q3	Q2	Q2

Step 2: Calculate energy of lattice site surrounding concerned element Q_i .
Energy is calculated using following formula:

$$E = J_{gb} \sum_{\langle i, j \rangle} (1 - \delta_{S_i S_j})$$

Grain boundary energy
Kronecker delta

Surrounding neighbors points

Step 3: The investigated cell changes the state to one of the available states/orientation.
The state/orientation is randomly generated from Ω available states/orientations.

Q1	Q1	Q2
Q3	Q4	Q2
Q3	Q2	Q2

Step 4: Calculate the change in energy Q_i caused by orientation changes

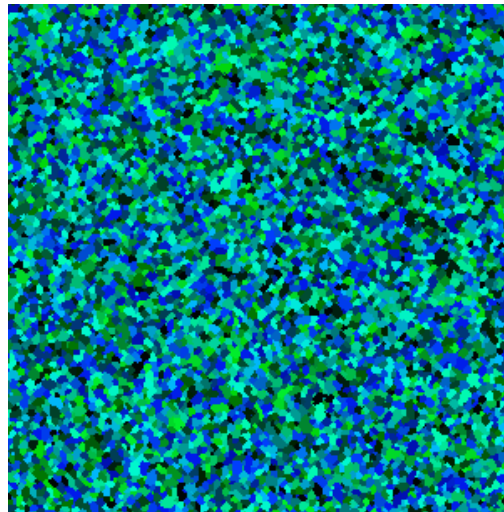
Step 5: The orientation change is accepted with the probability p :

$$p(\Delta E) = \begin{cases} 1 & \Delta E \leq 0 \\ 0 & \Delta E > 0 \end{cases}$$

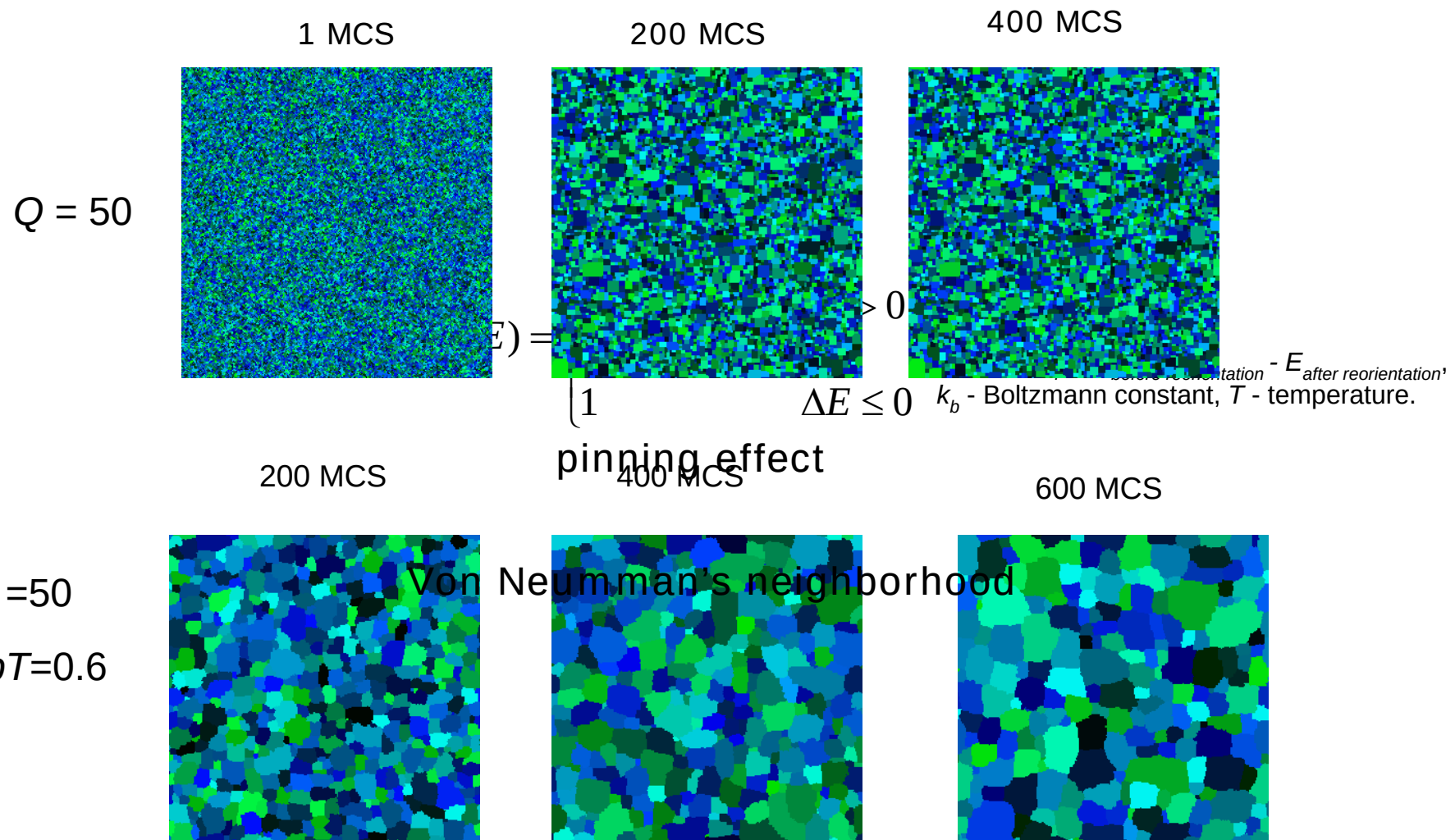
Q1	Q1	Q2
Q3	Q3	Q2
Q3	Q2	Q2

Q1	Q1	Q2
Q3	Q4	Q2
Q3	Q2	Q2

$$n_Q = 50$$

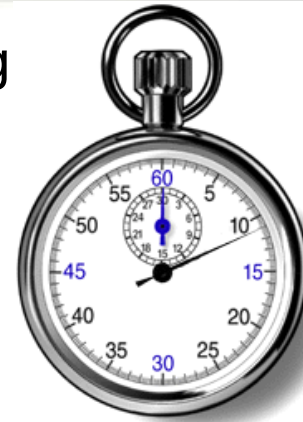
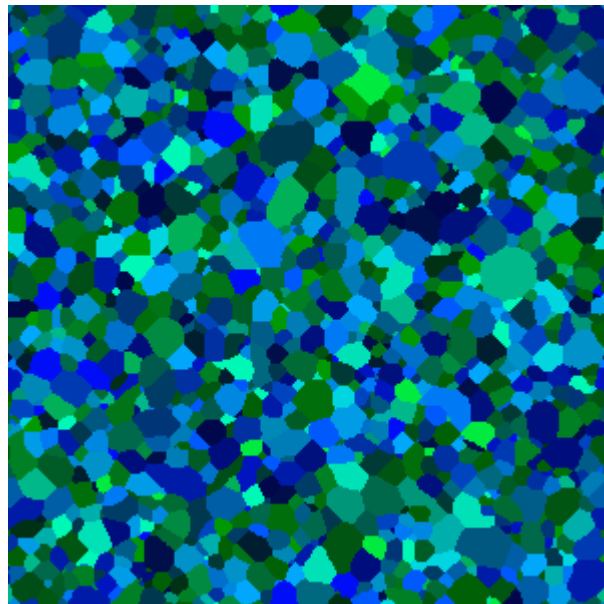


Moore's neighborhood

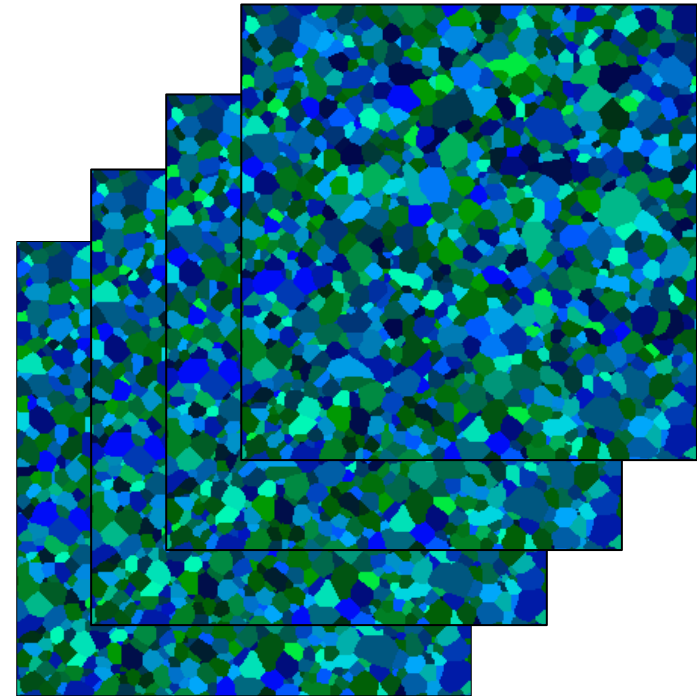


How can we improve computing time?

2 D – very time consuming



3 D – even worse



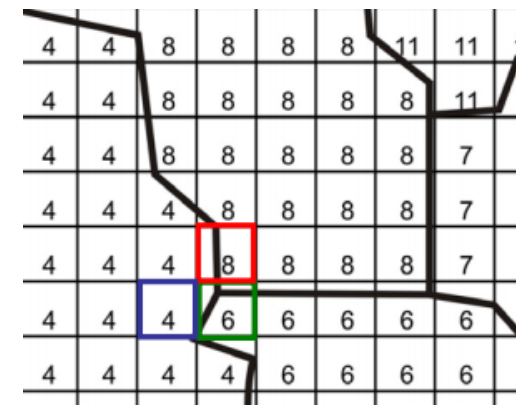
2 options to solve this issue

modification of the algorithm

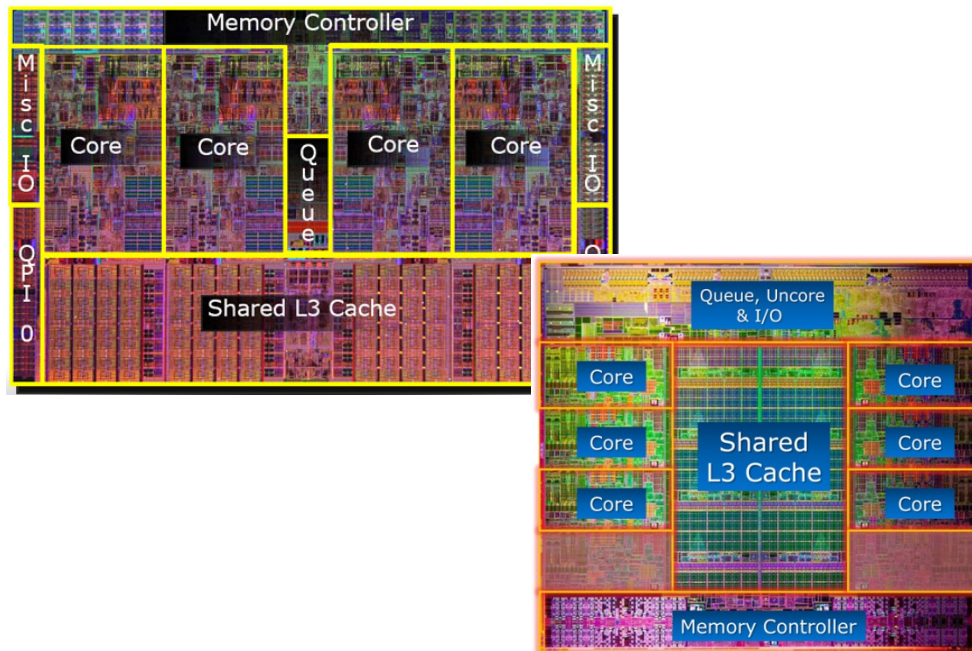
parallelization

Reduction of computing time :

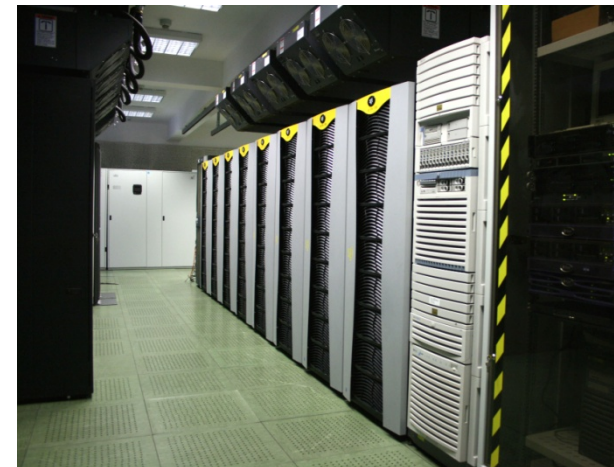
- consider only cells on grains boundary
- selection of a new orientation only from neighbors
- cell is randomly generated from $(W-k)$ available cells, where k is a number of cells already considered in currently MC step.



Multi threads application
single machine - openMP



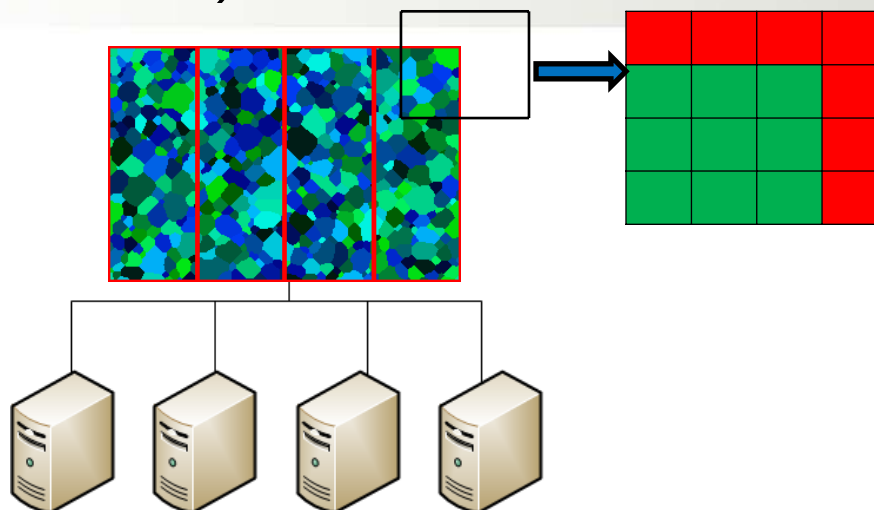
Multi node system - MPI



Parallelization idea – division work between threads (periodic boundary condition)

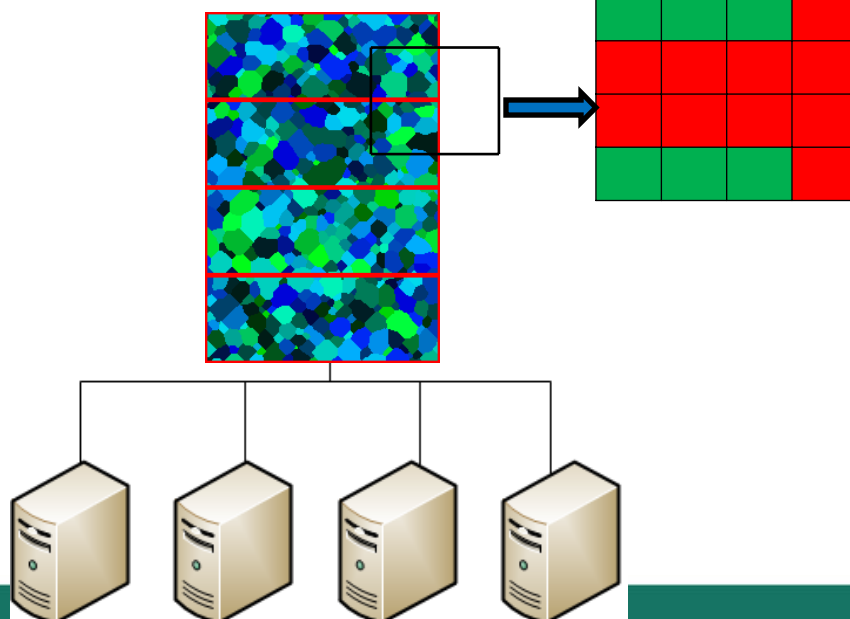
Case 1:

If($x > y$)



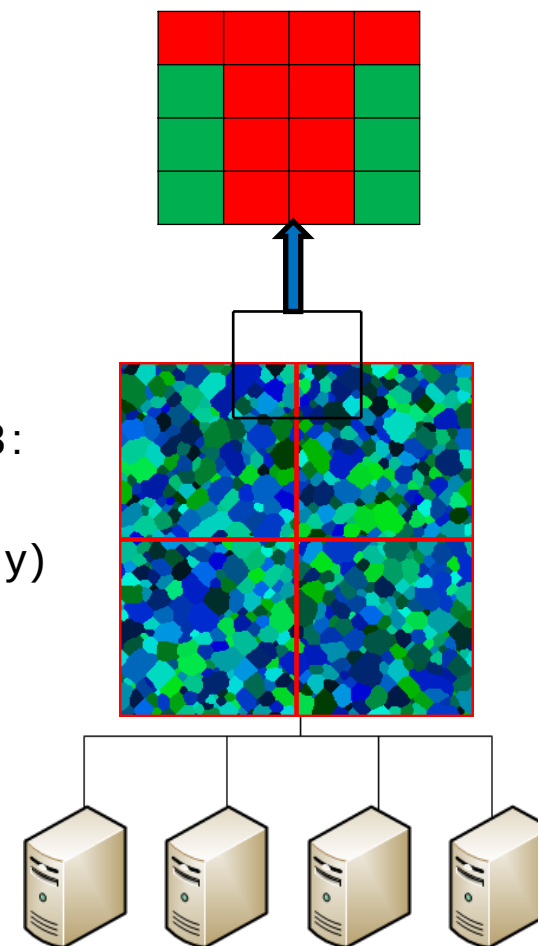
Case 2:

If($y > x$)

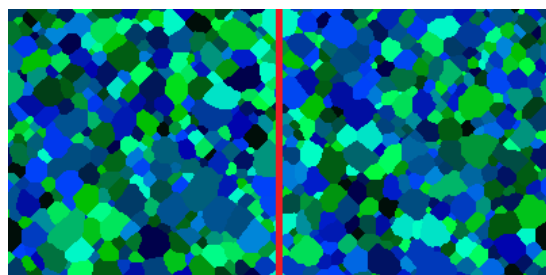


Case 3:

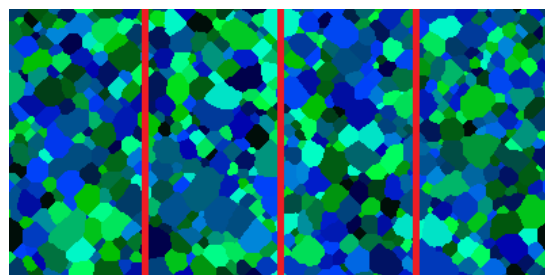
If($x = y$)



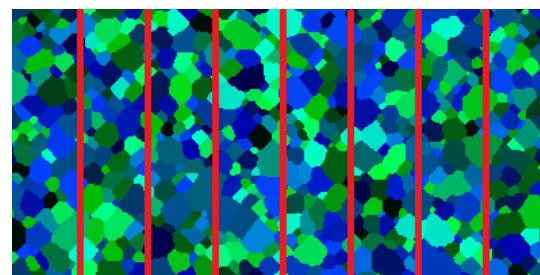
Case 1:



2 threads



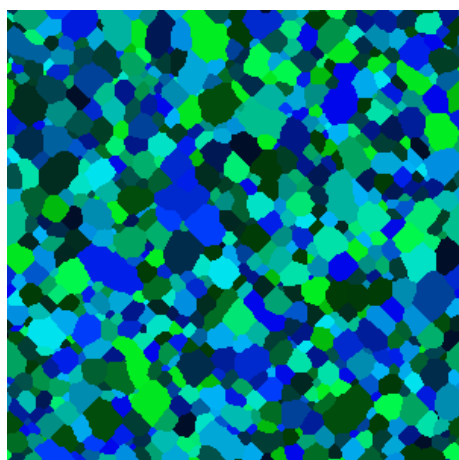
4 threads



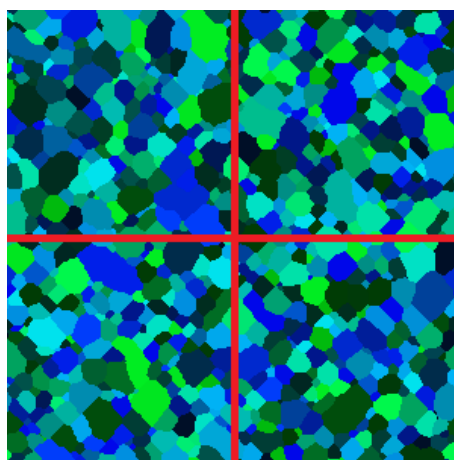
8 threads

n threads

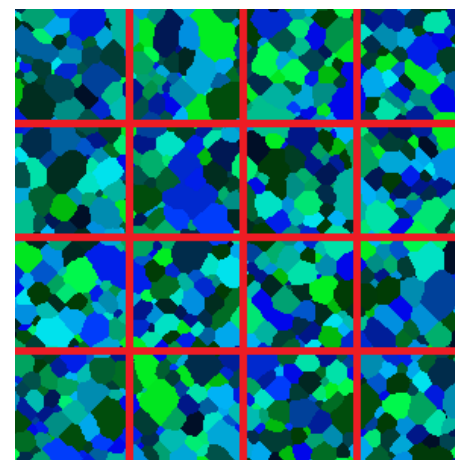
Case 3:



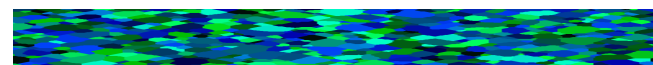
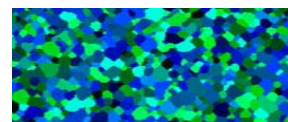
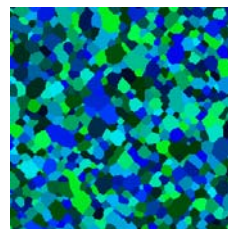
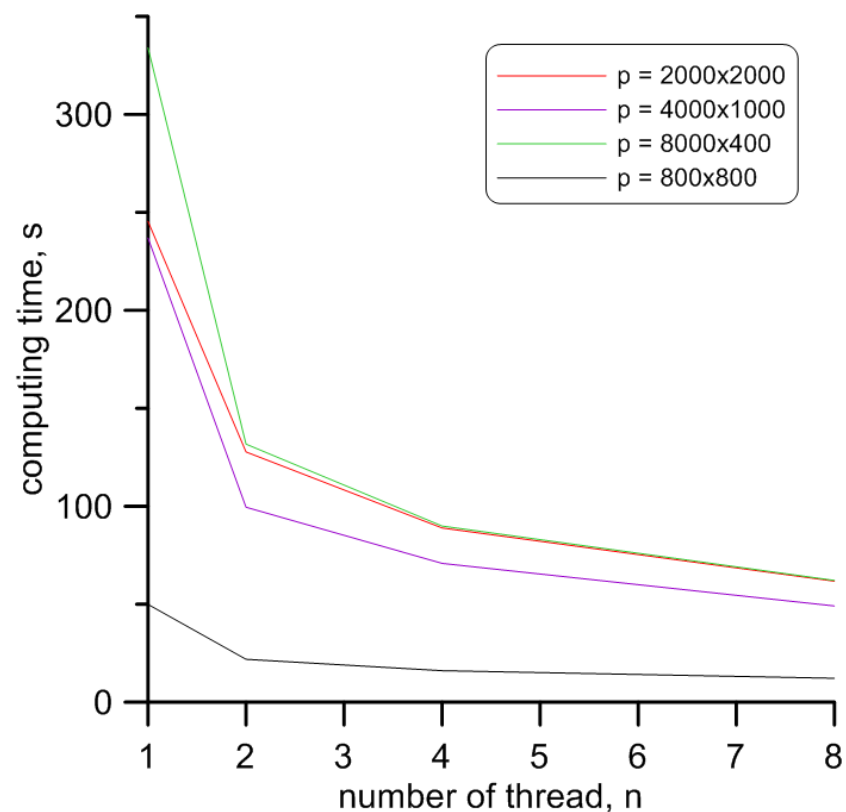
1 thread



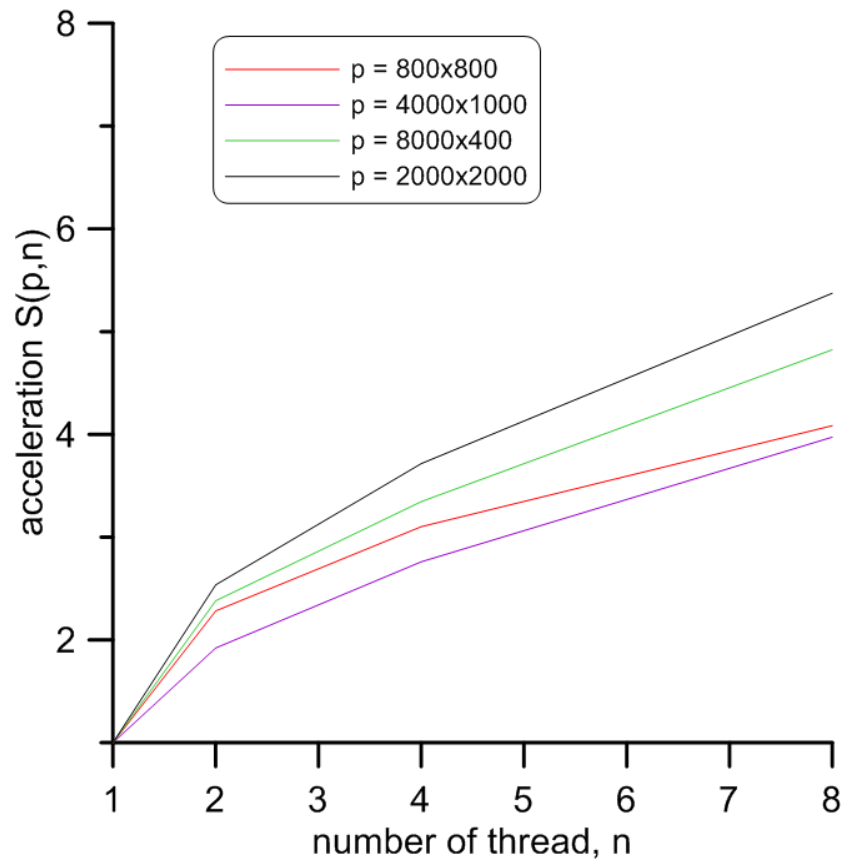
4 threads



16 threads



Computing time for 100MCS with different space size and number of thread

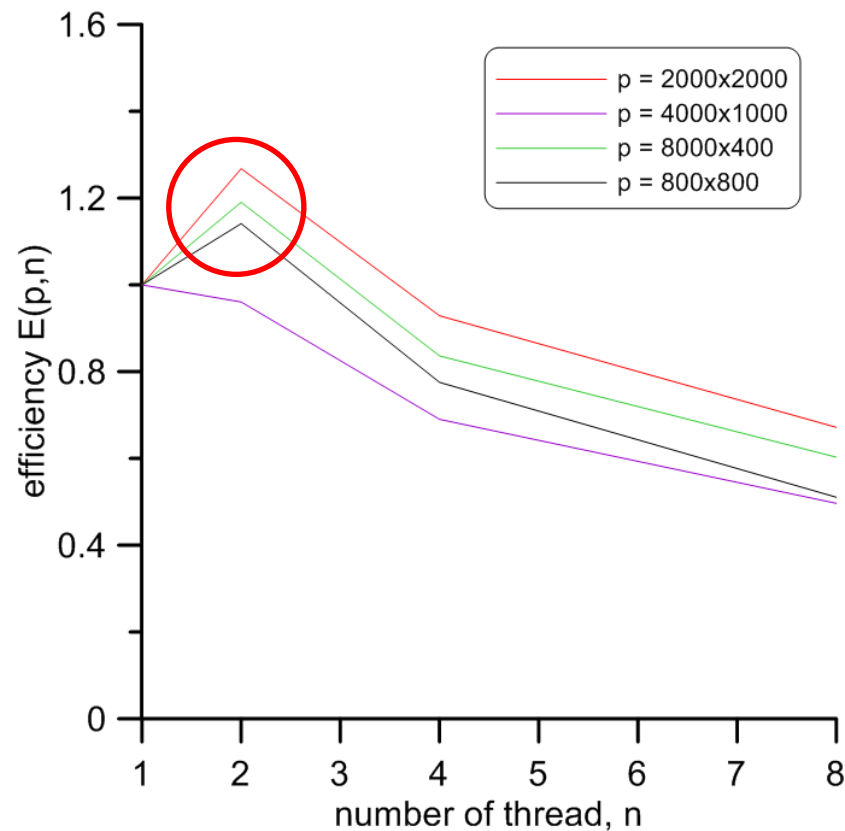


Acceleration :

$$S(p) = T_i / T_{||}(p)$$

Where: T_s - execution time for one processor,
 $T_{||}(p)$ - execution time for p processors

Acceleration as a function of
 thread number for 100MCS with
 different space size



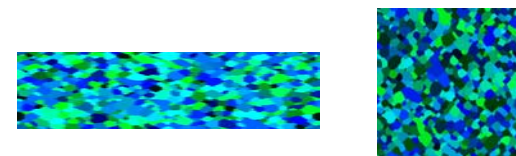
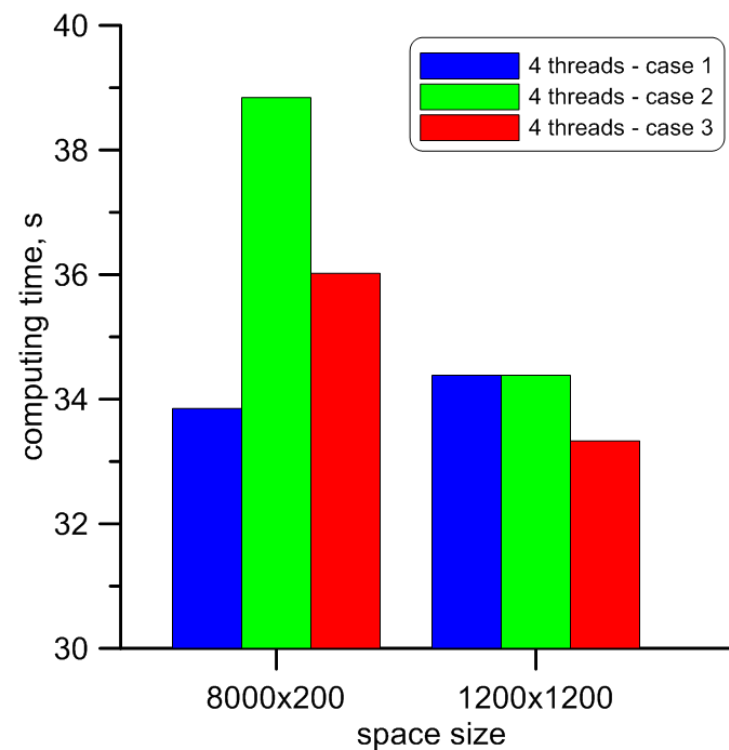
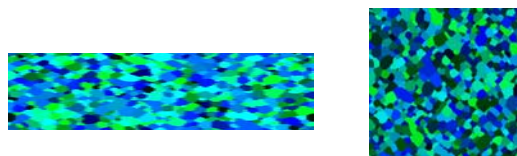
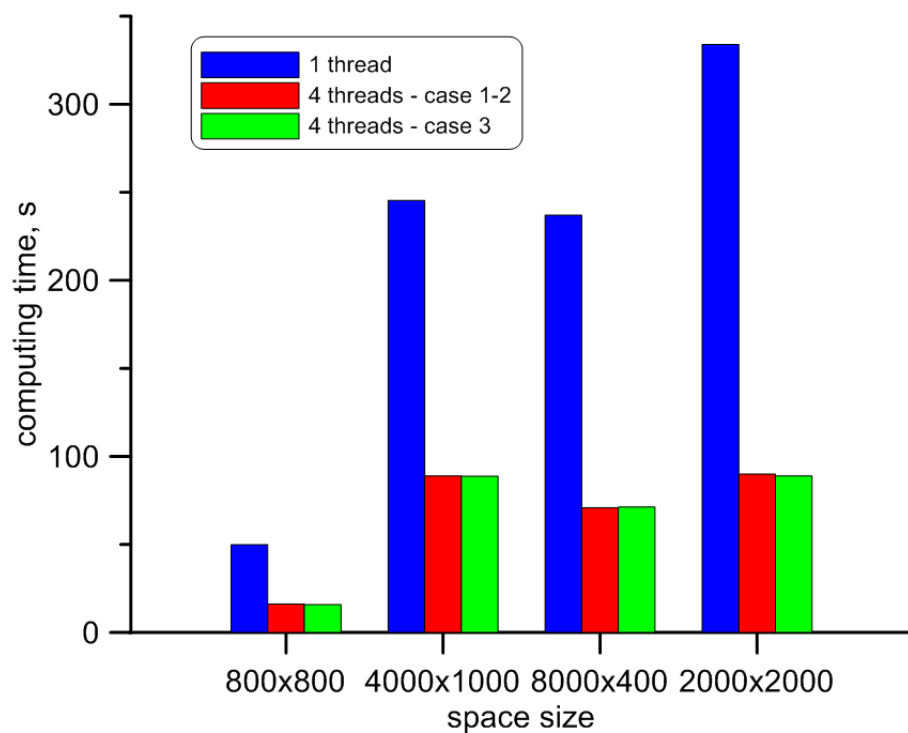
Parallel efficiency:

$$E(p) = S(p) / p$$

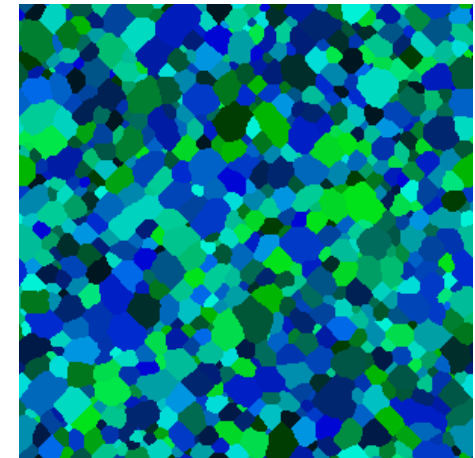
Where: $S(p)$ - acceleration, p processors number

Computing efficiency for 100MCS with different space size and number of thread

Comparison – three approaches to space division



- MC algorithm can be successfully applied to create polycrystalline material representation.
- The major problem of this method is long computation time.
- Computation time can be reduced by modification or parallelization of the algorithm
- Each MC space division scheme caused decrease in calculation time.
- The different division of the MC space between the threads significantly affect speedup calculation.
- Proper selection of space division can decrease calculation time almost 6 times.



- Scattering calculation on multi node system.
- Extension of different space division and parallel algorithm developed within this work to model static recrystallization phenomenon.

